Abstract

We present a novel technique for learning the mass matrices in samplers obtained from discretized dynamics that preserve some energy function. Our approach provides a simpler alternative to Riemannian preconditioning techniques, by using existing dynamics in the sampling step of a Monte Carlo EM framework, and learning the mass matrices in the M step with a novel online technique. Along with a novel stochastic sampler based on Nosé-Poincaré dynamics, we use this framework with standard Hamiltonian Monte Carlo (HMC) as well as newer stochastic algorithms such as SGHMC and SGNHT, and show strong performance on synthetic and real high-dimensional sampling scenarios; we achieve sampling accuracies comparable to Riemannian samplers while being notably faster.

Outline

- Hamiltonian Monte Carlo (HMC) for Bayesian sampling treats the target density as an "energy" function" augmented with auxiliary "momentum" parameters.
- A primary (hyper-)parameter of interest is the "mass" matrix of the kinetic energy term.
- Riemannian samplers exploit the underlying geometry by reformulating the mass in terms of the target parameters to be sampled [1, 2, 3].
- We propose an alternative way to learn the mass using Monte Carlo EM (MCEM) [4].
- MCEM is used to locally optimize MLE problems where the posterior probabilities required in the E step are not closed form.
- We perform existing dynamics derived from energy functions in the Monte Carlo E step while holding the mass fixed, and use the stored samples of the momentum term to learn the mass in the M step.

Experiments

- Synthetic : Parameter estimation for 1D standard normal distribution and 2D Bayesian logistic regression.
- Real world: Topic modeling with hierarchical Gamma processes (GPs).

Adaptive Bayesian Sampling with Monte Carlo EM

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Illustrative problem formulations

For the HMC / SGHMC energy function:	$\max_{M \succ 0}$	$\mathcal{L}(oldsymbol{ heta})$
For the SGNHT energy function:	$\max_{M \succ 0}$	$\mathcal{L}(oldsymbol{ heta})$



Representative results

Setup

 Synthetic Gaussian experiments 	•]
• 5,000 datapoints from standard normal distribution	I
 Normal-Wishart priors 	
 Metric tensor : Observed Fisher information plus negative 	– k
Hessian of prior	\mathbf{N}
 Synthetic Bayesian LR 	Η
• 5,000 datapoints from two Gaussians with means at	Н
[-1,1], [1,-1], and unit covariance	P
• Linear classifier with weights $(\omega_1, \omega_2) = [1, -1]$	
• For synthetics we use both HMC and stochastic	
samplers with MCEM augmentations.	$\overline{\mathbf{N}}$
• Topic modeling using GP construction from [5]	H
 Poisson factor analysis on term-document count matrix. 	Ч
• $\mathbf{D}_{V \times N} = \operatorname{Poi}(\mathbf{\Phi}\mathbf{\Theta}), \ \theta_{n,k} \sim \Gamma(r_k, \frac{p_j}{1-p_i}), \ r_k s \text{ being the GP}$	T 1
weights.	R
 Perplexities measured for 20-Newsgroups and Reuters 	
corpora, with stochastic samplers and MCEM.	

 $-(1/2)\mathbf{p}^T M^{-1}\mathbf{p} - (1/2)\log|M|$ $-(1/2)\mathbf{p}^T M^{-1}\mathbf{p} - (1/2)\log|M| + \mu(\xi - \bar{\xi})^2/2$

Example: HMC-EM

```
Input: \theta^{(0)}, \epsilon, LP\_S, S\_count
\cdot Initialize M;
repeat
  · Sample \mathbf{p}^{(t)} \sim N(0, M);
  for i = 1 to LP\_S do
    \cdot \mathbf{p}^{(i)} \leftarrow \mathbf{p}^{(i+\epsilon-1)}, \ \boldsymbol{\theta}^{(i)} \leftarrow \boldsymbol{\theta}^{(i+\epsilon-1)};
    \cdot \mathbf{p}^{(i+\frac{\epsilon}{2})} \leftarrow \mathbf{p}^{(i)} - \frac{\epsilon}{2} \nabla_{\boldsymbol{\theta}} H(\boldsymbol{\theta}^{(i)}, \mathbf{p}^{(i)});
   \cdot \boldsymbol{\theta}^{(i+\epsilon)} \leftarrow \boldsymbol{\theta}^{(i)} + \frac{\overline{\epsilon}}{2} \nabla_{\mathbf{p}} H(\boldsymbol{\theta}^{(i)}, \mathbf{p}^{(i+\frac{\epsilon}{2})});
    \cdot \mathbf{p}^{(i+\epsilon)} \leftarrow \mathbf{p}^{(i+\frac{\epsilon}{2})} - \frac{\epsilon}{2} \nabla_{\boldsymbol{\theta}} H(\boldsymbol{\theta}^{(i+\epsilon)}, \mathbf{p}^{(i+\frac{\epsilon}{2})});
  end for
 · Set (\boldsymbol{\theta}^{(t+1)}, \mathbf{p}^{(t+1)}) from (\boldsymbol{\theta}^{LP} - S + \epsilon, \mathbf{p}^{LP} - S + \epsilon)
      using Metropolis-Hastings
  · Store MC-EM sample \mathbf{p}^{(t+1)};
  if (t+1) \mod S_count = 0 then
    · Update M using MC-EM samples;
  end if
  · Update S_count as described in the paper;
until forever
```

RMSE and runtimes

Per-iteration runtimes and RMSE for HMC, HMC-EM and RHMC on synthetic data. Synthetic Gaussian dataset.

I ETHOD	$RMSE(\mu)$	$\overline{\text{RMSE}(\tau)}$	TIME		
[MC	0.0196	0.0197	$0.417 \mathrm{MS}$		
[MC-EM	0.0115	0.0104	0.423MS		
CHMC	0.0111	0.0089	$5.748\mathrm{MS}$		
Synthetic regression dataset.					
I ETHOD	$RMSE(W_0)$) $RMSE(V$	V_1) Time		
[MC	0.0456	0.1290	1.435MS		
[MC-EM	0.0145	0.0851	1.428MS		
$\mathbf{L}\mathbf{HMC}$	0.0091	0.0574	1550MS		

methods.



Results, contd.



Post-burnin time (seconds)

• Test perplexities plotted against wall-clock time for the 20-Newsgroups dataset.

• The MCEM algorithms converge to perplexities within 3% of SGR-NPHMC [2], but are an order of magnitude faster.

References

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